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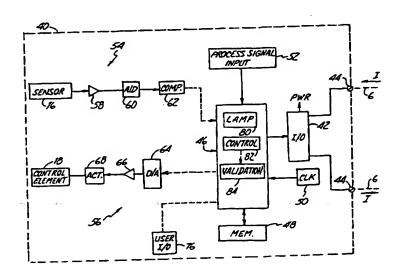
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(54) Title: DEVICE IN A PROCESS SYSTEM FOR VALIDATING A CONTROL SIGNAL FROM A FIELD DEVICE



(57) Abstract

A device (40) in a process control system (2) includes a memory (48) for storing a series of sensed process variables and command outputs representative of a learned process cycle. Comparison circuitry (80) compares recent process information to learned process information stored in the memory (48) and responsively provides a validity output signal. A method includes learning a cycle of a process to provide learned process information which comprises stored process variables and stored control signals over a time period, measuring a process variable in the process and responsively calculating the control output, storing the process variable in the control output to provide recent process information, and comparing the recent process information to the learned process information and responsively providing a validity output signal.

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DEVICE IN A PROCESS SYSTEM FOR VALIDATING A CONTROL SIGNAL FROM A FIELD DEVICE

BACKGROUND OF THE INVENTION

The present invention relates to devices which couple to process control loops of the type used in industry. More specifically, the invention relates to validating a control signal from a field device.

Process control loops are used in industry to control operation of a process, such as an oil refinery. A transmitter is typically part of the loop and is located in the field to measure and transmit a process variable such as pressure, flow or temperature, for example, to control room equipment. A controller such as a valve controller is also part of the process control loop and controls position of a valve based upon a control signal received over the control loop or controllers control generated internally. Other electric motors or solenoids, for example. The control room equipment is also part of the process control loop such that an operator or computer in the control room is capable of monitoring the process based upon process variables received from transmitters in the field and responsively controlling the process by sending control signals to the appropriate control devices. process device, which may be part of a control loop, is a portable communicator which is capable of monitoring and transmitting process signals on the process control loop. These are often used to configure devices which form the loop.

It is desirable to validate the control signals in the process control system thereby improving the reliability of the entire loop. Typically, the prior art has been limited to simple validation techniques, such as monitoring a control signal and

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sounding an alarm or providing a safety shutdown if the control signal exceeds predefined limits. Another prior art technique is to generate a redundant control signal using the same or a different control algorithm and compare the two control signals. The control signal is invalidated if it differs from the redundant signal.

SUMMARY OF THE INVENTION

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A device in a process control system includes a memory for storing a series of sensed process variables and command outputs representative of a 10 learned process cycle. Comparison circuitry compares recent process information to learned information stored in the memory and responsively provides a validity output signal. A method in accordance with one aspect of the invention includes 15 learning a cycle of a process to provide learned process information which comprises stored process variables and stored control signals over a time period, measuring a process variable in the process and responsively calculating the control output, storing the process 20 variable in the control output to provide recent process information, and comparing the recent information to the learned process information and responsively providing a validity output signal.

BRIEF DESCRIPTION OF THE DRAWINGS

Figure 1 is a simplified diagram showing a process control loop including a transmitter, controller, hand-held communicator and control room.

Figure 2 is a block diagram of a process device in accordance with the present invention.

Figure 3 is a simplified block diagram showing steps in accordance with the present invention.

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Figure 4A shows a learning cycle and Figure 4B shows an operation cycle for two process variables and a control signal.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

The present invention provides a technique for validating control signals in a process control system Process variables are to control process variables. typically the primary variables which are being As used herein, process controlled in a process. variable means any variable which describes condition of the process such as, for example, pressure, turbidity, product level, temperature, pH, position, current, any motor vibration, characteristic of the process, etc. Control signal means any signal (other than a process variable) which is used to control the process. For example, control signal means a desired process variable value (i.e. a setpoint) such as a desired temperature, pressure, flow, product level, pH or turbidity, etc., which is adjusted by a controller or used to control the process. Additionally, a control signal means, calibration values, alarms, alarm conditions, the signal which is provided to a control element such as a valve position signal which is provided to a valve actuator, an energy level which is provided to a heating element, a solenoid on/off signal, etc., or any other signal which relates to control of the process. Process devices include any device which forms part of or couples to a process control loop and is used in the control or monitoring of a process.

Figure 1 is a diagram showing an example of a process control system 2 which includes process piping 4 carrying a process fluid and two wire process control loop 6 carrying loop current I. Transmitter 8,

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controller 10 (which couples to a final control element in the loop such as an actuator, valve, a pump, motor or solenoid), communicator 12, pc 13 and control room 14 are all part of process control loop 6. understood that loop 6 is shown in one configuration and 5 any appropriate process control loop may be used such as a 4-20 mA loop, 2, 3 or 4 wire loop, multi-drop loop and a loop operating in accordance with the HART®, Fieldbus or other digital or analog communication protocol. operation, transmitter 8 senses a process variable such 10 as flow using sensor 16 and transmits the sensed process variable over loop 6. The process variable may be received by controller/valve actuator 10, communicator 12, pc 13 and/or control room equipment 14. Controller 10 is shown coupled to valve 18, and is capable of 15 controlling the process by adjusting valve 18 thereby changing the flow in pipe 4. Controller 10 receives a control input over loop 6 from, for example, control room transmitter 14, 8 or communicator responsively adjusts valve 18. In another embodiment, 20 controller 10 internally generates the control signal based upon process signals received over loop Communicator 12 may be the portable communicator shown in Figure 1 or may be a permanently mounted process unit which monitors the process and performs computations. 25 Process devices include, for example, transmitter 8, controller 10, communicator 12 and control room 14 shown in Figure 1. Another type of process device is a PC, programmable logic unit (PLC) or other computer coupled to the loop using appropriate I/O circuitry to allow 30 monitoring, managing, and/or transmitting on the loop. Any of the process devices 8, 10, 12, 13 or 14 shown in Figure 1 may include control signal validation circuitry in accordance with the present invention.

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Figure 2 is a block diagram of a process device 40 forming part of loop 6. Device 40 is shown generically and may comprise any of process device 8-14. preferred embodiment, device 40 comprises pc Control room equipment 14 may comprise, for example, a DCS system implemented with a PLC and controller 10 may also comprise a "smart" motor and pump. Process device 40 includes I/O circuitry 42 coupled to loop 6 at terminals 44. I/O circuitry has preselected input and output impedances known in the art to facilitate appropriate communication from and to device 40. Device 40 includes microprocessor 46, coupled to I/O circuitry 42, memory 48 coupled to microprocessor 46 and clock 50 Microprocessor coupled to microprocessor 46. receives a process signal input 52. Input 52 is intended to signify input of any process signal, and as explained above, the process signal input may be a process variable, or a control signal and may be received from loop 6 using I/O circuitry 42 or may be generated internally within field device 40. device 40 is shown with a sensor input channel 54 and a control channel 56. In many instances, a transmitter such as transmitter 8 will exclusively include sensor input channel 54 while a controller such as controller 10 will exclusively include a control channel 56. Other devices on loop 6 such as communicator 12 and control room equipment 14 may not include channels 54 and 56. It is understood that device 40 may contain a plurality of channels to monitor a plurality of process variables and/or control a plurality of control elements as 30 appropriate.

Sensor input channel 54 includes sensor 16, sensing a process variable and providing a sensor output to amplifier 58 which has an output which is digitized WO 98/29785 PCT/US97/23496

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by analog to digital converter 60. Channel 54 is typically used in transmitters such as transmitter 8. Compensation circuitry 62 compensates the digitized signal and provides a digitized process variable signal to microprocessor 46.

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When process device 40 operates a controller such as controller 8, device 40 includes control channel 56 having control element 18 such as a valve, for example. Control element 18 is coupled to microprocessor 46 through digital to analog converter 64, amplifier 66 and actuator 68. Digital to analog converter 64 digitizes a command output microprocessor 46 which is amplified by amplifier 66. Actuator 68 controls the control element 18 based upon the output from amplifier 66. In one embodiment, actuator 68 is coupled directly to loop 6 and controls a source of pressurized air (not shown) to position control element 18 in response to the current I flowing through loop 6.

20 In one embodiment, I/O circuitry 42 provides a power output used to completely power all the circuitry in process device 40 using power received from loop 6. Typically, field devices such as transmitter 8, or controller 10 are powered from the loop 6 while communicator 12 or control room 14 has a separate power 25 As described above, process signal input 52 provides a process signal to microprocessor 46. process signal may be a process variable from sensor 16, the control output provided to control element 18, or a 30 control signal, process variable or diagnostic signal received over loop 6, or a process signal received or generated by some other means such as another I/O channel.

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A user I/O circuit 76 is also connected to microprocessor 46 and provides communication between device 40 and a user. User I/O circuit 76 includes, for example, a display for output and a keypad for input. Typically, communicator 12 and control room 14 includes I/O circuit 76 which allows a user to monitor and input process signals such as process variables, control signals (setpoints, calibration values, alarms, alarm conditions, etc.) A user may also use circuit 76 in cormunicator 12 or control room 14 to send and receive signals between transmitter process Further, such circuitry controller 10 over loop 6. in transmitter could be directly implemented controller 10 or any other process device 40.

Microprocessor 46 acts in accordance with instructions stored in memory 48 and provides, in some embodiments, a sensor compensation function 80 and/or a control function 82. Furthermore, microprocessor 46 provides a control signal validation function 84 in accordance with the present invention. The command signal to be validated may be received, for example, through any of the various inputs to microprocessor 46 described above.

Figure 3 is a simplified block diagram 80 of a command validation function in accordance with the present invention performed by microprocessor 46 in response to instructions stored in memory 48 shown in Figure 2. The function is initiated during a repeatable process cycle 82 and enters a process learning cycle 84. Process learning cycle 84 includes block 86 during which process signal(s) are obtained and stored in memory 48 at block 88. More than one process pattern may be obtained and stored in memory 48. Cycle 84 may be performed during commissioning of the process control

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computer storage device 22 is run on the computer workstation 18. As will be described in detail below, when running an installation routine controlled by the software the installer is prompted to identify the particular network interface device 16 and to input a build location code, a delivery location code and a unique identifier for the computer workstation 18. Subsequently, by using this data, the installation routine is able to connect the computer workstation 18 to the network 10 via the network interface device 16. The installation routine then automatically installs an appropriate computer operating system from a remote computer operating system installation source held in the network data store 14 onto the disk memory 20 of the computer workstation 18. As will be described below, the installation routine is adapted to configure the computer operating system in dependence on the delivery location code. The build location code refers to where the build process is to be carried out, whilst the delivery location code refers to where the built computer workstation is to be located.

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An overview of the installation routine will now be described with reference to the flow chart of Figure 2. As indicated, having inserted the installation disk and switched the computer workstation on, the installer is prompted to input a build location code and a delivery location code in step 100. An environment database in a look-up table stored on the installation disk is then interrogated with the build location code and the delivery location code (step 102) to obtain build location specific variables and delivery location specific variables which are stored by the computer workstation in step 104. The installer is also prompted to enter a unique identifier for the computer workstation (step 106). Using the build location specific variables the installation routine connects the computer workstation to the network in step 108 and accesses an installation account on the server. A master installation script held with the computer operating system installation source on the network data store is copied onto the disk memory of the computer workstation in step 110. The copy of the installation script is then modified in dependence on the build location specific variables and on the delivery location specific variables (step 112) to create a dedicated installation script. The computer operating system is then installed and configured using the computer operating system installation source setup routine with the dedicated installation script in step 114.

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The installation and configuration step 114 of Figure 2 is expanded upon in the flow chart of Figure 3. As shown, the computer operating system installation source is copied from the network data store onto the disk memory (such as a hard disk) of the computer workstation in step 200. The setup routine then disconnects from the network and reboots the computer workstation in step 202. After the reboot of the computer workstation, the setup routine installs the computer operating system using the dedicated installation script (step 204). The computer operating system is then configured in dependence upon the dedicated installation script in step 206. Any additional software components such as e-mail and office application suites specified in the installation script are installed from the network data store at this time (step 208). The setup routine also cleans up the disk memory of the computer workstation by deleting any unnecessary files in step 210. The setup routine ends once the computer workstation has a complete computer operating system ready for use at the delivery location.

The schematic of Figure 4 includes the computer hardware arrangement of Figure 1 in addition to a network 30 and a network server 32 to which the computer workstation 18 is intended to be connected. The network 10 may be a part of the same LAN as the network 30, it may be a part of the same WAN as the network 30 connected by a telecommunications system, or there may be no network connection to the network 30. If there is a connection between the network 10 and the network 30 that the computer workstation 18 is intended to be used upon, then the installation routine registers the computer workstation 18 by its unique identifier with the network 30 and network server 32 where the computer workstation 18 is to be used. If there is no connection to the network 30 that the computer workstation 18 is intended to be used upon the registration is re-run when the computer is first started at the delivery location.

A more specific example of the present invention will now be described with reference to Figures 4 and 5. In this example, the network 10 is an ethernet network, with network servers 12, 32 operating under Microsoft Windows NT Server operating system V.4 and the computer operating system installation source is Microsoft Windows NT workstation. The computer storage device 22 is an MS-DOS formatted disk holding an MS-DOS v.6.22 operating system kernel and files necessary to boot the computer workstation 18, the

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installation routine, the environment database and TCP/IP network drivers for each selectable network interface device 16. The computer workstation 18 is a Hewlett-Packard Vectra XM/4 5/166 Personal Computer with 32MB of random access memory. The disk memory 20 of the computer workstation is a 1.2GB hard disk drive. The network interface device 16 is a 3COM Etherlink 2 3C503/16 ethernet network card installed in the computer workstation 18.

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When the computer workstation 18 is booted with the computer storage device 22 inserted in the computer's disk drive, the operating system kernel on the computer storage device 22 takes control of the boot routine and prompts the user to select the network interface device 16 used from a list of supported network interface devices using the MS-DOS v.6.22 start-up menu facility in step 300. The TCP/IP network drivers corresponding to a network interface device selected from the list are copied to default file names (step 302) so that the install routine may access any of the supported network interface devices without knowledge of the specific type. The boot routine then runs the installation routine in step 304. The installation routine accepts an input of a build location code (step 305) and a delivery location code (step 306). The build location code and delivery location code are cross-referenced with a list of allowable locations in respective steps 307, 308 and if the locations are not on the list, a list of the allowable locations is displayed in respective steps 309, 310 and the installer is prompted to re-enter the code in respective steps 305, 306. If six incorrect attempts at entering an allowable location are made the installation routine ends and reports an error in respective steps 309a and 310a. After a valid build location code and a valid delivery location code are entered, the installation routine accepts an input of a unique identifier for the computer workstation (step 311) to be later used as its DNS address. The installation routine interrogates the environment database with the build location code and the delivery location code in step 312 to obtain build location specific variables and delivery location specific variables. The variables relate to environment and network specific settings for the two locations, as can be seen from Table 1.

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Code	Location	Server	Share	File System	Keyboard Layout	Logon Domain	Join Domain	Timezone
CR	Crewe	UK_CRID	ID4	NTFS	UK	UK_G	UK_C	GMT
GR	Greenford	UK_ID	ID4	NTFS	UK	UK_G	UK_1	GMT
REM	Remote Build Site	UKGW	ID4	NTFS	UK	UK_REM	UK_REM	GMT
ик	GW UK at Stockley	UK_ID4	ID4	NTFS	UK	UK_G	UK_1	GMT
UK_1	GW UK Backup at Stockley	UKB_ID4	ID4	NTFS	UK	UKB_G	UKB_1	GMT
us	US RTP Primary	US0001	ID4	NTFS	US	US1	US_D	GMT-5

Table 1

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The build location specific variables "server" and "share" define the server and network data store holding the computer operating system installation source. If, for example, the build location UK is entered, the computer operating system installation source would be installed from ID4 on the UK ID4 server.

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Using these variables in combination with the TCP/IP drivers and the unique identifier, the installation routine logs the computer workstation onto the network in step 313. The IP address for the computer is obtained from the server using DHCP (dynamic host configuration protocol) and the unique identifier is used for the DNS address. A computer disk format utility is run to format the disk memory 20 of the computer workstation 18. A master installation script stored on the network data store with the computer operating system software source is copied onto the disk memory (step 314). An example of a master installation script is shown below:

25 [Unattended]

OemPreinstall = yes

OemSkipEula = yes

NoWaitAfterTextMode = 1

NoWaitAfterGUIMode = 1

30 FileSystem =

JoinDomain =

```
ExtendOEMPartition = 1.nowait
       ConfirmHardware = no
       NtUpgrade = no
       Win31Upgrade = no
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       TargetPath = WINNT
       OverwriteOemFilesOnUpgrade = no
       KeyboardLayout =
       [GUIUnattended]
10
       TimeZone =
       [OEM Ads]
       Banner = "Glaxo Wellcome. GIS ID4 v3.0 Installation.*Windows NT v4.0 Workstation."
       Background = gis.bmp
15
       [UserData]
       FullName = "Glaxo Wellcome"
       OrgName = "Glaxo Wellcome"
       ComputerName =
20
       [Display]
       ConfigureAtLogon = 0
       BitsPerPel = 8
       XResolution = 800
25
       YResolution = 600
       VRefresh = 60
       AutoContirm = 1
       [Network]
30
       InstallProtocols = Glaxo Protocol List
       InstallInternetServer = Glaxo_Internet_List
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CreateComputerAccount =

[Glaxo_Protocol_List]
TC = TCPIP Parameters

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[TCPIP_Parameters]
MCP=Yes

[Glaxo Internet List]

InstallNETSTP = 0

InstallMOSAIC = 0

The installation routine then modifies the copied script in dependence on the build location specific variables and on the delivery location specific variables (step 315) to create a dedicated installation script. In the above example, the script fields shown in bold are edited by inserting the delivery location specific variables, the field names corresponding to the column headings of Table 1. The unique identifier is entered as the ComputerName.

The installation routine then proceeds in step 316 to accept inputs relating to the selection of additional software to be installed. Such additional software may include drivers to access other network protocols, office application suites and e-mail client software. The installation routine ends by running the Windows NT set-up routine held with the computer operating system source on the network store. The Windows NT set-up routine is run in step 317 in an unattended installation mode using the dedicated installation script to provide answers to questions usually asked during a manual set-up. The set-up routine proceeds substantially as has been described with reference to Figure 3.

Windows NT requires that each computer workstation has its own DNS (Domain Name Service) address and that the address is registered with the network domain in which the computer workstation is to be used. With reference to the example of Figure 5, the configuration Step 206 of Figure 3 is expanded upon in the flow chart of Figure 6. Prior to the set-up routine ending, the routine reconnects the computer workstation to the

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network 10 using the newly installed computer operating system (step 412) and an attempt is made (step 414) to connect to the network where the computer workstation is intended to be used. If this is successful, the unique identifier for the computer is registered as the computer workstation's DNS address with the Windows NT network domain and server that the computer workstation is intended to be used upon in step 416. The computer workstation then disconnects from the networks (step 418) and is ready for use upon delivery to the location where it is intended to be used. If the attempt is not successful, the installation fails.

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Where an outside organisation is contracted to supply and configure the computer workstation, a connection to the network where the computer workstation is intended to be used is not possible. To overcome this, a remote build site code relating to the outside organisation's own network is used for the build location code (REM in Table 1). In step 315 of Figure 5, when the copied script is modified, the location specific variables relating to the remote build site code are used for both the build location specific variables and the delivery location specific variables. The delivery location code entered is stored for later use. When an attempt is made to connect to the computer workstation to the network domain and server upon which the computer workstation is intended to be used (step 414). the connection is actually made to the remote build site network permitting the set-up routine to complete. When the computer workstation is delivered by the outside organisation to the delivery location, the configuration of the computer operating system is updated in dependence on the stored delivery location code. The unique identifier of the computer workstation is then registered with the Windows NT network domain and server that the computer workstation is intended to be used upon at the delivery location according to the previously described steps 414 to 418 of Figure 6.

Claims:

- 1. A method of installing a computer operating system, comprising the steps of running an installation routine on a computer in which the installation routine accepts user inputs defining a delivery location and is operative to connect the computer to an operating system installation source held on a remote computer, retrieve a copy of a master installation script held on the remote computer, and modify the copied master installation script in dependence on a number of variables associated with the delivery location to create a dedicated installation script, and subsequently installing automatically the computer operating system using the dedicated installation script.
- 2. A method according to claim 1, in which the installation routine is operative to retrieve the computer operating system from the remote computer and subsequently disconnect the computer from the remote computer, whereby the computer is then rebooted and the computer operating system installed using the dedicated installation script.
- 3. A method according to claim 1 or 2, in which the installation routine also accepts user inputs defining a build location corresponding to the location of the remote computer where the operating system installation source is held.

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- 4. A method according to any preceding claim, in which the remote computer is connected to a network.
- 5. A method according to claim 4, in which the delivery location is on the same network as the remote computer.
 - 6. A method according to claim 5, in which the delivery location is on a different network to the remote computer.
- 30 7. A method according to any preceding claim, in which the installation routine also accepts a user input defining a unique identifier for the computer.

- 8. A method according to claim 7, further comprising the step of registering the computer with a network using the unique identifier.
- 9. A method according to any preceding claim, in which the installation routine is initiated by running a computer program held on a storage device.
 - 10. A method according to claim 9. in which the storage device is a computer disk which is inserted into a drive of the computer.
- 11. A method according to claim 9 or 10, in which the storage device holds a database containing a number of delivery specific variables associated with a number of possible delivery locations, whereby the delivery specific variables are used to modify the master installation script.
- 15 12. A method according to claim 11, in which the database contains a number of build specific variables associated with a number of possible build locations which are used to connect the computer to the remote computer.
- 13. A method according to any of claims 9 to 12, in which the storage device stores a number of network drivers from which the user selects an appropriate driver to enable connection to the remote computer.
 - 14. A method according to any preceding claim, in which the computer connects to the remote computer by the internet.

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- 15. A system for installing a computer operating system comprising:
- a computer:
- a network to which the computer may be connected;
- a remote computer connected to the network which holds an operating system installation source and a master installation script file; and,
- a storage device which holds a set of computer executable instructions and a number of files for performing an installation routine in accordance with the method of any preceding

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claim when run on the computer.

- 16. A system for installing a computer operating system according to claim 15, in which the storage device is a computer disk.
- 17. A program storage device readable by a machine and encoding a program of instructions and a number of files for executing the method of a specified one of claims 1 through 14.
- 18. A program storage device according to claim 17, in which the machine is a general purpose computer.

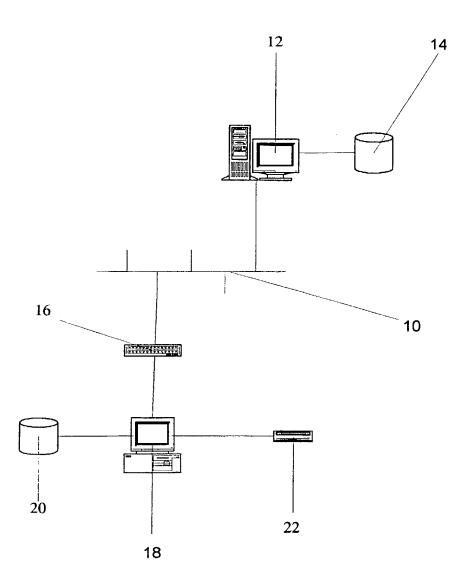
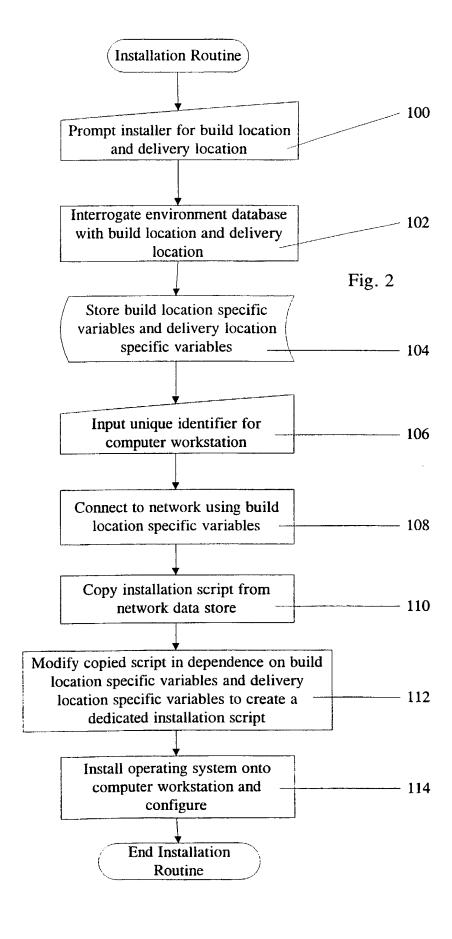
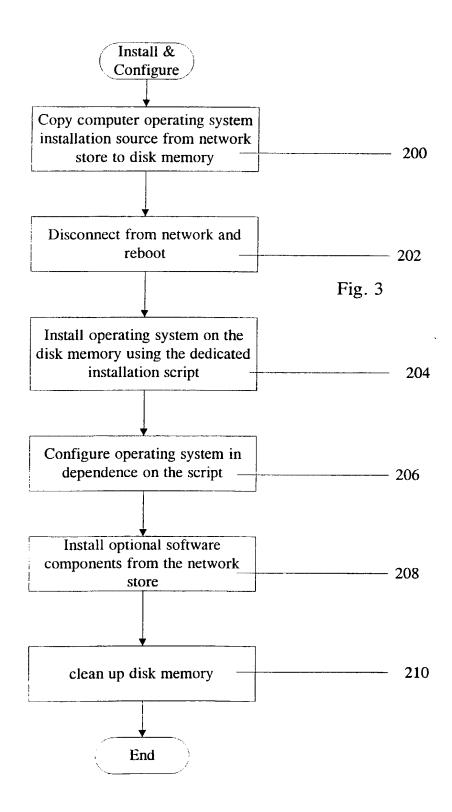


Fig. 1





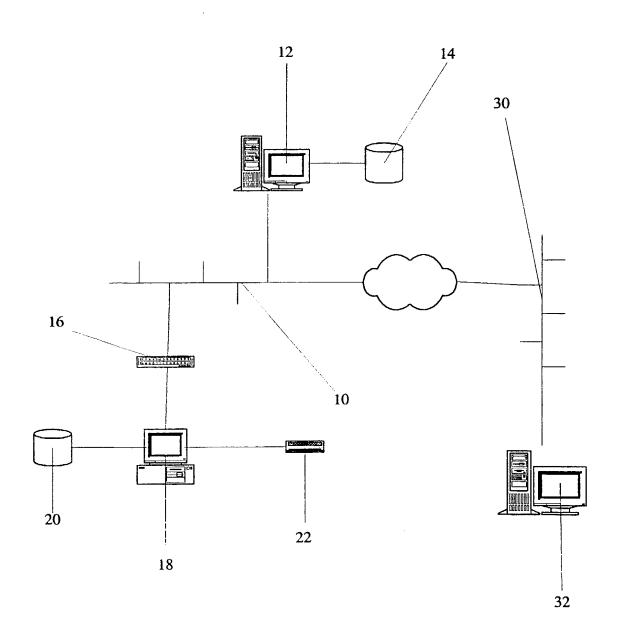
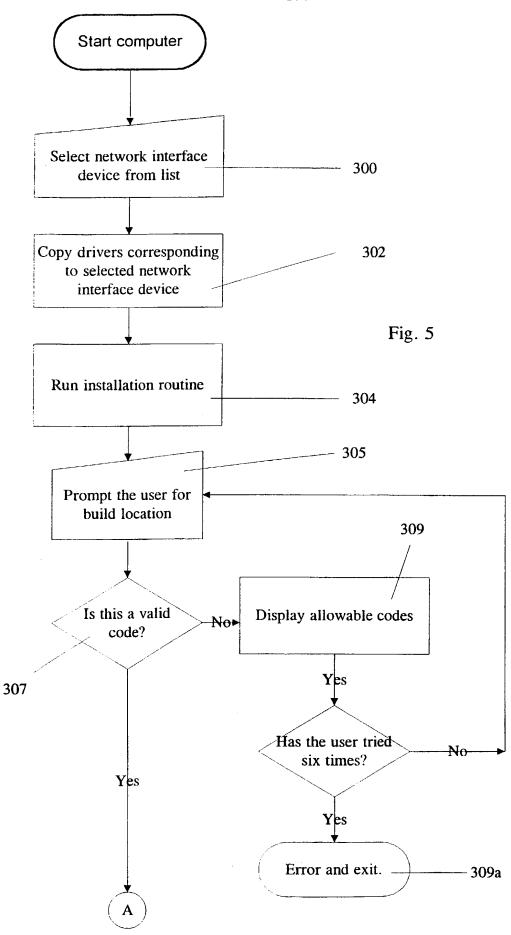
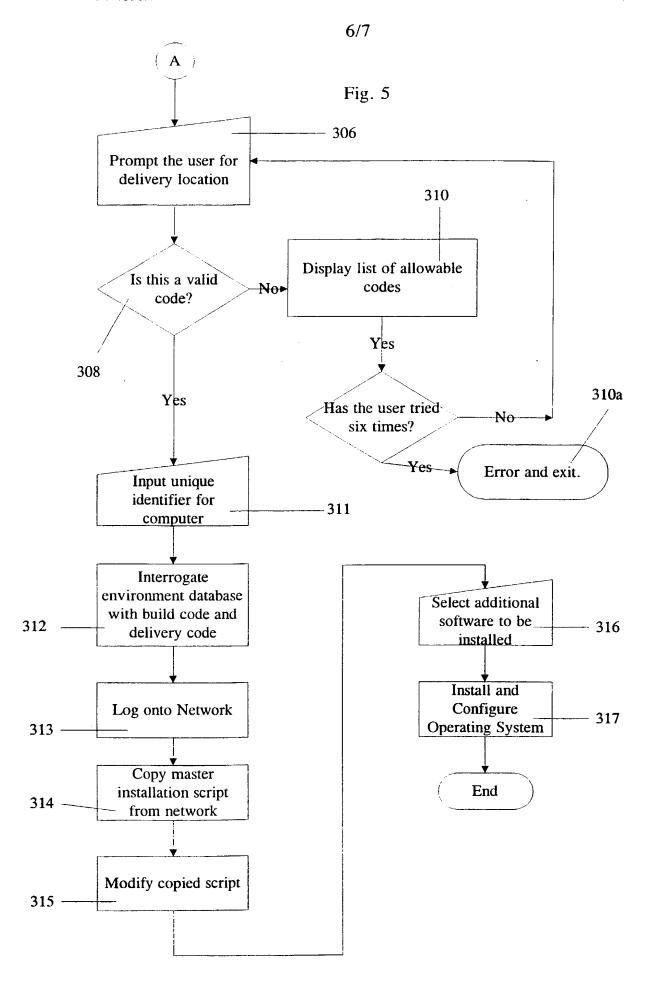
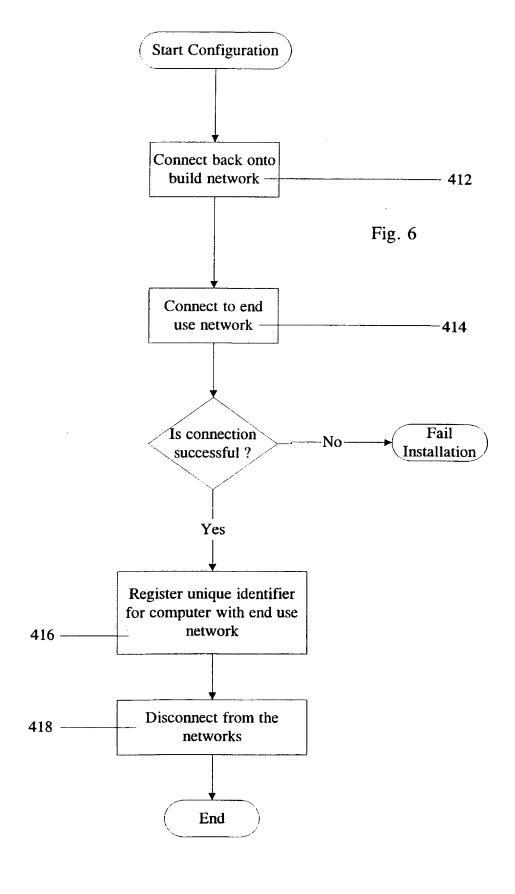


Fig. 4







INTERNATIONAL SEARCH REPORT

Internal Application No PCT/GB 98/01356

	FICATION OF SUBJECT MATTER G06F9/44		ļ
According to	o International Patent Classification(IPC) or to both national classi	fication and IPC	
B. FIELDS	SEARCHED		
Minimum do IPC 6	ocumentation searched (classification system followed by classific G06F H04L	ation symbols)	
Documental	tion searched other than minimumdocumentation to the extent tha	t such documents are included in the fields sea	arched
Electronic d	ata base consulted during the international search (name of data	base and, where practical, search terms used)	
			:
C. DOCUM	ENTS CONSIDERED TO BE RELEVANT		
Category °	Citation of document, with indication, where appropriate, of the	relevant passages	Relevant to claim No.
Х	"REMOTE SOFTWARE INSTALLATION IBM TECHNICAL DISCLOSURE BULLET vol. 34, no. 10A, 1 March 1992,	IN,	1,15
Α	82-84, XP000302233 see the whole document		2-14, 16-18
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	see the whole document		
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X Furt	ther documents are listed in the continuation of box C.	X Patent family members are listed	in annex.
"A" docum	ategories of cited documents:	"T" later document published after the inte or priority date and not in conflict with cited to understand the principle or th	the application but
"E" earlier filling	dered to be of particular relevance document but published on or after the international date ent which may throw doubts on priority claim(s) or	invention "X" document of particular relevance; the cannot be considered novel or canno involve an inventive step when the do	t be considered to
which citatio "O" docum	n is cited to establish the publicationdate of another on or other special reason (as specified) nent referring to an oral disclosure, use, exhibition or	"Y" document of particular relevance; the cannot be considered to involve an ir document is combined with one or ments, such combination being obvic	claimed invention wentive step when the ore other such docu-
"P" docum	means nent published prior to the international filing date but than the priority date claimed	in the art. "&" document member of the same patent	·
L	actual completion of theinternational search	Date of mailing of the international sea	arch report
9	9 November 1998	16/11/1998	
Name and	mailing address of the ISA European Patent Office, P.B. 5818 Patentlaan 2	Authorized officer	
	NL - 2280 HV Rijswijk Tel. (+31-70) 340-2040, Tx. 31 651 epo nl,	Cichra, M	

INTERNATIONAL SEARCH REPORT

Internat Application No
PCT/GB 98/01356

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